

liquid resource types for verification and synthesis

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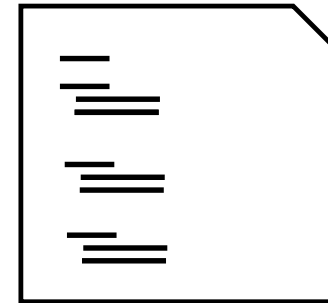
UCSD CSE
Computer Science and Engineering

program synthesis

specification



code



type-driven program synthesis



example: compress a list

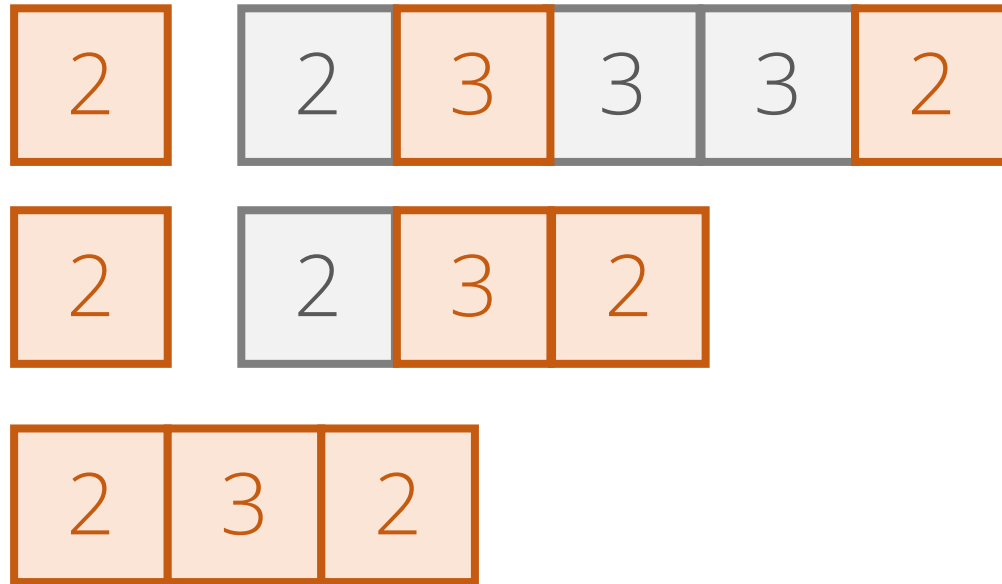
Input:



Output:



example: compress a list



synthesizing compress

specification



code



compress: specification

```
compress :: xs: List a → List a
```

compress: specification

```
compress :: xs: List a → {v:CList a | elems v = elems xs}
```


compress: generated solution

```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →  
    match compress ys with  
    Nil → Cons y Nil  
    Cons z zs → if y == z  
                 then compress ys  
                 else Cons y (Cons z zs)
```

compress: generated solution

```
compress xs =  
  match xs with  
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    Cons z zs → if y == z           Cons z zs  
                 then compress ys  
                 else Cons y (Cons z zs)
```

exponential!

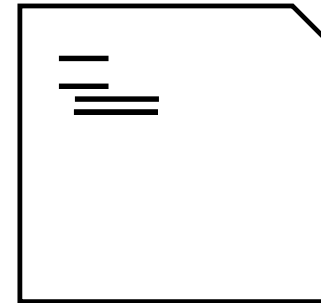
synthesizing efficient programs

specification

code

we have:

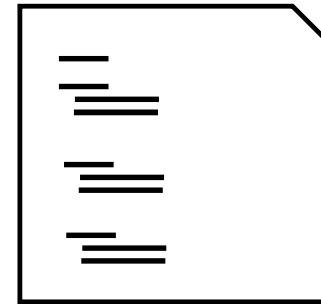
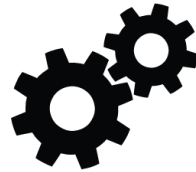
compress a list



$O(2^{|xs|})$

we want:

compress a list
in linear time



$O(|xs|)$

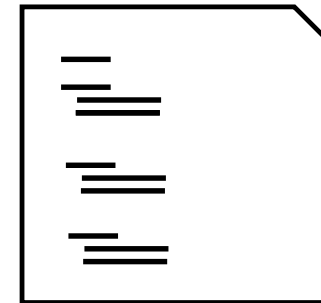
synthesizing efficient programs

specification

resyn

code

liquid
resource
types



$O(|xs|)$

this talk

1. liquid types + resource bounds
2. type checking
3. value-dependent bounds
4. non-linear bounds

[PLDI'19]

under review

this talk

1. liquid types + resource bounds
2. type checking
3. value-dependent bounds
4. non-linear bounds

types + refinements

$$\{ v:\text{Int} \mid \frac{\theta \leq v}{} \}$$

↑
refinement

types + refinements

$\{ v:\text{Int} \mid 0 \leq v \}$



natural numbers

types + refinements

List { v :Int | $0 \leq v$ }



lists of nats

types + refinements + resources

$$\{ v:\text{Int} \mid \frac{\theta \leq v}{\text{refinement}} \mid \frac{1}{\text{potential}} \}$$

types + refinements + resources

List { v: Int | 0 ≤ v | 1 }

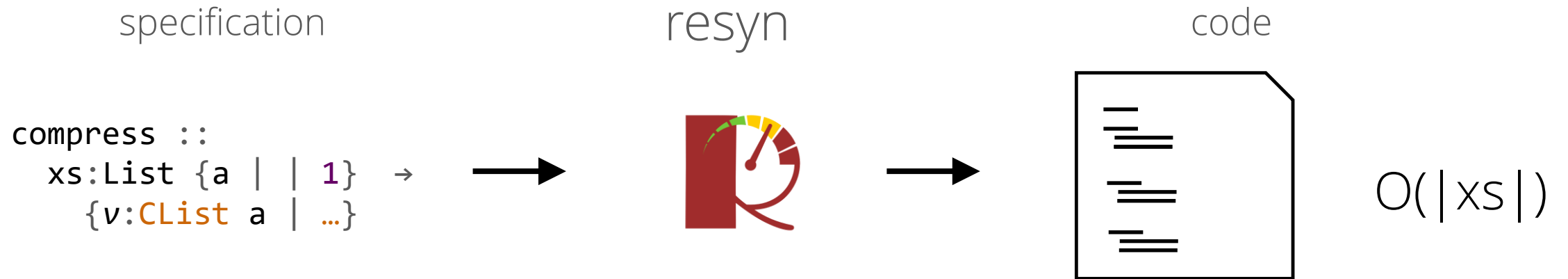


lists of nats with length units of potential

compress: liquid resource type

```
compress :: xs:List {a | | 1} →  
          {v:CList a | elems v = elems xs}
```

synthesizing linear compress



this talk

1. liquid types + resource bounds
2. type checking
3. value-dependent bounds
4. non-linear bounds

checking compress (exponential)

```
compress :: List {a | 1} → List a
```



```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →  
    match compress ys with  
    Nil → Cons y Nil  
    Cons z zs → if y == z  
                  then compress ys  
                  else ...
```

checking compress (exponential)

List a



```
compress: List {a||1} → List a  
xs: List {a||1}
```

```
compress xs =
```

```
  match xs with
```

```
    Nil → Nil
```

```
    Cons y ys →
```

```
      match compress ys with
```

```
        Nil → Cons y Nil
```

```
        Cons z zs → if y == z
```

```
                      then compress ys
```

```
                      else ...
```

use available resources
to pay for recursive calls
and terms that require potential

checking compress (exponential)

List a



```
compress: List {a||1} → List a  
y: {a||1}  
ys: List {a||1}
```

```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →  
    match compress ys with  
    Nil → Cons y Nil  
    Cons z zs → if y == z  
                  then compress ys  
                  else ...
```

checking compress (exponential)

List a



compress: List {a||1} → List a
ys: List {a||1}

```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →  
    match compress ys with  
    Nil → Cons y Nil  
    Cons z zs → if y == z  
                  then compress ys  
                  else ...
```

checking compress (exponential)

List a



compress: List {a||1} → List a
ys: List {a||1}

```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →  
    match compress (ys :: List {a||p}) with  
    Nil → Cons y Nil  
    Cons z zs → if y == z  
                  then compress (ys :: List {a||q})  
                  else ...
```

checking compress (exponential)

List a



compress: List {a||1} → List a
ys: List {a||1}

Constraints: $\exists p, q:$

$$1 = p + q$$

1. total potential must be partitioned into two uses:

```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →
```

```
    match compress (ys :: List {a||p}) with
```

```
      Nil → Cons y Nil
```

```
      Cons z zs → if y == z
```

```
        then compress (ys :: List {a||q})
```

```
        else ...
```

checking compress (exponential)

List a



compress: List {a||1} → List a
ys: List {a||1}

Constraints: $\exists p, q:$

$$1 = p + q$$

$$p \geq 1$$

```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →
```

2. p must be enough to call
compress

```
  match compress (ys :: List {a||p}) with  
  Nil → Cons y Nil  
  Cons z zs → if y == z  
               then compress (ys :: List {a||q})  
               else ...
```

checking compress (exponential)

List a



compress: List {a||1} → List a
ys: List {a||1}

```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →
```

3. q must be enough to call
compress

```
  match compress (ys :: List {a||p}) with  
  Nil → Cons y Nil  
  Cons z zs → if y == z  
               then compress (ys :: List {a||q})  
               else ...
```

Constraints: $\exists p, q:$

$$1 = p + q$$

$$p \geq 1$$

$$q \geq 1$$

checking compress (exponential)

List a



```
compress xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →
```

```
    match compress (ys :: List {a||p}) with
```

```
      Nil → Cons y Nil
```

```
      Cons z zs → if y == z
```

```
        then compress (ys :: List {a||q})
```

```
        else ...
```

compress: List {a||1} → List a

ys: List {a||1}

Constraints: $\exists p, q:$

$$1 = p + q$$

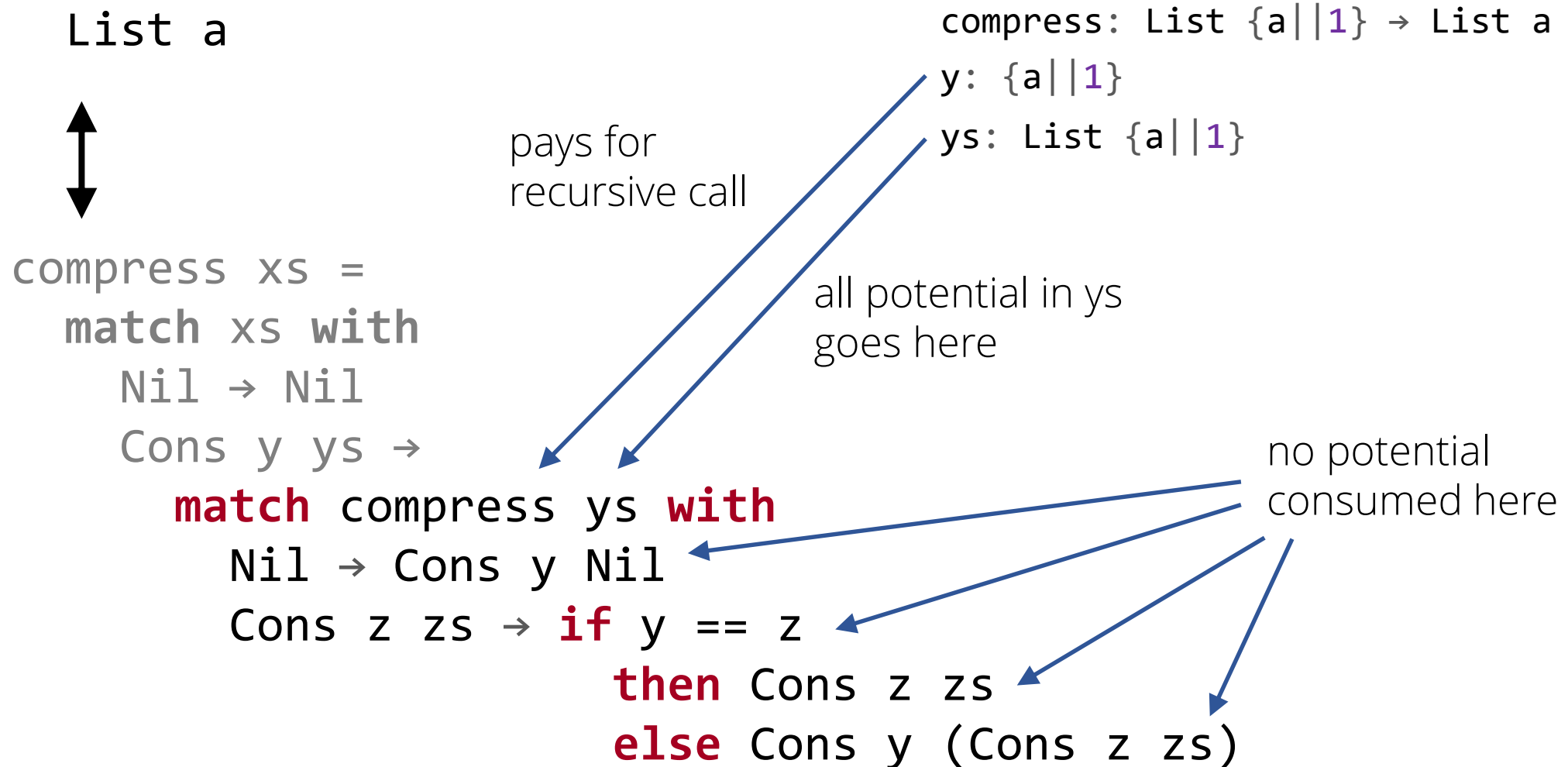
$$p \geq 1$$

$$q \geq 1$$

SMT solver: UNSAT!



checking compress (linear)



subtyping

$$\frac{[[\Gamma]] \Rightarrow r \Rightarrow r' \quad [[\Gamma]] \Rightarrow p \geq p'}{\Gamma \vdash \{B \mid r \mid p\} <: \{B \mid r' \mid p'\}}$$

sharing

$$\frac{\begin{array}{l} \Gamma_1 \vdash e :: \text{List } T' \\ \Gamma_2 \vdash e_1 :: T \\ \Gamma_2, x: T', xs: \text{List } T' \vdash e_1 :: T \end{array}}{\Gamma_1 + \Gamma_2 \vdash \text{match } e \text{ with } e_1; \lambda x \ xs. e_2 :: T}$$

resource polymorphism for free

```
compress :: List {a | | 1} → List a
```

```
compress2 :: List {b | | 2} → List b
```

```
compress2 xs = compress (compress xs)
```

resource polymorphism for free

```
compress :: List {a | | 1} → List a
```

```
compress2 :: List {b | | 2} → List b
```

```
compress2 xs = compress[b / a] (compress[{b| |1} / a] xs)
```

this talk

1. liquid types + resource bounds
2. type checking
3. value-dependent bounds
4. non-linear bounds

value-dependent potential

$\{ v:\text{Int} \mid 0 \leq v \mid v \}$

nat with potential equal to its value

insert into sorted list

```
insert :: x:a → xs:SList {a | | 1}
        → SList a
insert x xs =
  match xs with
  Nil → Cons x Nil
  Cons y ys →
    if x ≤ y
    then Cons x xs
    else Cons y (insert x ys)
```

makes one step
per element < x?

insert: dependent bound

```
insert :: x:a → xs:SList {a | | v < x ? 1 : 0}
        → SList a
```

```
insert x xs =
```

```
  match xs with
```

```
    Nil → Cons x Nil
```

```
    Cons y ys →
```

```
      if x ≤ y
```

```
        then Cons x xs
```

```
        else Cons y (insert x ys)
```

$y: \{a \mid | v < x ? 1 : 0\}$

pays for
recursive call



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insertion sort

```
insert :: x:a  
  → xs:SList {a | |v < x ? 1 : 0}  
  → SList a
```

```
insert x xs =  
  match xs with  
  Nil → Cons x Nil  
  Cons y ys →  
    if x ≤ y  
    then Cons x xs  
    else Cons y (insert x ys)
```

makes one step
per element < x

```
sort :: ???
```

```
sort xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →  
    insert y (sort ys)
```

super-linear!

makes one step per out-of-
order pair of elements

sorted list via **inductive refinements**

```
data List a where  
  Nil :: List a  
  Cons :: h:a →  
         t:List a →  
         List a
```

sorted list via **inductive refinements**

```
data SList a where
  Nil :: SList a
  Cons :: h:a →
         t:SList a →
         SList a
```

sorted list via **inductive refinements**

```
data SList a where  
  Nil :: SList a  
  Cons :: h:a →  
         t:SList {a | h ≤ v} →  
         SList a
```

quadratic list via **inductive potentials**

data SList a **where**

Nil :: SList a

Cons :: h:a →

t:SList {a | h ≤ v} →

SList a

data QList a **where**

Nil :: QList a

Cons :: h:a →

t:QList {a || 1} →

QList a

generality via **abstract refinements**

```
data SList a where  
  Nil :: SList a  
  Cons :: h:a →  
    t:SList {a | h ≤ v} →  
    SList a
```

```
data List a <p: a → a → Bool> where  
  Nil :: List a <p>  
  Cons :: h:a →  
    t: List {a | p h v} <p> →  
    List a <p>
```

```
type SList a = List a < _0 ≤ _1 >
```

generality via **abstract potentials**

```
data List a
    <p: a → a → Bool> where
Nil :: List a <p>
Cons :: h:a →
    t: List {a | p h v} <p> →
    List a <p>
```

```
type SList a
    = List a < _0 ≤ _1 >
```

```
data List a
    <q: a → a → Int> where
Nil :: List a <q>
Cons :: h:a →
    t: List {a || q h v} <q> →
    List a <q>
```

```
type QList a
    = List a < _1 < _0 ? 1 : 0 >
```


insertion sort

```
insert :: a  
  → SList {a | |v < x ? 1 : 0}  
  → SList a
```

```
insert x xs =  
  match xs with  
  Nil → Cons x Nil  
  Cons y ys →  
    if x ≤ y  
    then Cons x xs  
    else Cons y (insert x ys)
```

```
sort :: List a <_1 < _0 ? 1 : 0 >  
  → SList a
```

```
sort xs =  
  match xs with  
  Nil → Nil  
  Cons y ys →  
    insert y (sort ys)
```

liquid resource types

1. liquid types + resource bounds
 2. type checking
 3. value-dependent bounds
 4. non-linear bounds
- + talk to me about:
- “logarithmic” bounds via trees
 - linear types for program synthesis